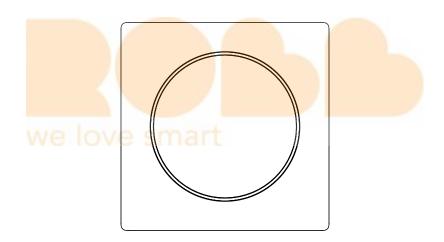


OPERATING MANUAL





FIBARO WALLI ROLLER SHUTTER FGWREU-111



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1: Important safety information

Read this manual before attempting to install the device!

Failure to observe recommendations included in this manual may be dangerous or cause a violation of the law. The manufacturer, Fibar Group S.A. will not be held responsible for any loss or damage resulting from not following the instructions of operating manual.

DANGER OF ELECTROCUTION!

The device is designed to operate in electrical home installation. Faulty connection or use may result in fire or electric shock.



• All works on the device may be performed only by a qualified and licensed electrician. Observe national regulations.

Even when the device is turned off, voltage may be present at its terminals. Any maintenance introducing changes into the configuration of connections or the load must be always performed with disabled fuse.



To avoid risk of electrical shock, do not operate the device with Δ wet or moist hands.

Do not modify!



Do not modify this device in any way not included in this manual.

Other devices

The manufacturer, Fibar Group S.A. will not be held responsi- ble for any damage or loss of warranty privileges for other connected devices if the connection is not compliant with their manuals.

This product is intended for indoor use only in dry locations.

Do not use in damp or wet locations, near a bathtub, sink, shower, swimming pool, or anywhere else where water or moisture are present.

CAUTION!

It is not recommended to operate all of the roller blinds simultaneously. For safety reasons, at least one roller blind should be controlled independently, providing safe escape route in case of emergency.

Not a toy!



This product is not a toy. Keep away from children and animals!

2: Description and features

2.1: Description

FIBARO Walli Roller Shutter is a smart wall switch designed to control motors of roller blinds, awnings, venetian blinds and other single phase, AC powered devices via Z-Wave network.

It measures active power and energy consumed by the controlled load.

You can install it with provided cover plate and switch button or other compatible.

2.2: Main features

- Can be used with:
 - » roller blinds ,
 - » venetian blinds,
 - » awnings,
 - » blind motors with electronic or mechanical limit switches.
- Can be used with FIBARO Walli covers or other compatible (see "Parts compatibility" on page 36):
 - » GIRA System 55 (Standard 55, E2, Event, Event Clear),
 - » Legrand Céliane,
 - » Schneider Odace.
- Active power and energy metering.
- Supports Z-Wave network Security Modes: S0 with AES-128 encryption and S2 Authenticated with PRNG-based encryption.
- Works as a Z-Wave signal repeater (all non-battery operated devices within the network will act as repeaters to increase reliability of the network).
- May be used with all devices certified with the Z-Wave Plus certificate and should be compatible with such devices produced by other manufacturers.

| : | ן The | de | evice is | a Sec | urity | Enabled | l Z- | Wave Plu | ıs prod | duct |
|-----|---------|-----|-----------|---------|---------|---------|------|------------------------|---------|------|
| 1 | and | а | Securit | y En | abled | Z-Wave | e C | Wave Plเ Controller | r must | be |
| use | ed in d | orc | ler to fu | illy ut | ilize t | he prod | uct | - •• | | |

3: Specifications

| Power supply | 110-230V~ 50/60 Hz |
|---|---|
| Rated load current | 4A for motors with compensated power factor (inductive loads) |
| | 13A for resistive loads |
| Compatible load types | (M) single-phase AC motors |
| | resistive loads |
| Required limit switches | electronic or mechanic |
| Recommended external overcurrent protection | 10A type B circuit breaker (EU) 13A type B circuit breaker (Sweden) |
| For installation in boxes | Ø = 60mm, depth ≥ 40mm |
| Recommended wires | cross-section area between 1.5-4.0mm², stripped 11.5-13mm of insulation |
| Operating temperature | 0-35°C |
| Ambient humidity | 10–95% RH without condensation |
| Radio protocol | Z-Wave (500 series chip) |
| Radio frequency band | 868.0-868.6MHz; 869.7-870.0MHz |
| Max. transmitting power | +6dBm |
| Range | up to 50m outdoors up to 40m indoors |
| we love smar | (depending on terrain and building structure) |
| Dimensions (Height x Width x Depth) | 86 x 86 x 51 mm |
| Compliance with EU directives | RoHS 2011/65/EU RED 2014/53/EU |

Radio frequency of individual device must be same as your Z-Wave controller. Check information on the box or consult your dealer if you are not sure.

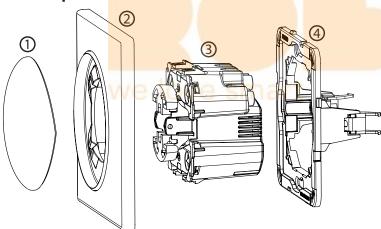
4: Installation

4.1: Before installation

Connecting the device in a manner inconsistent with this a manual may cause risk to health, life or material damage.

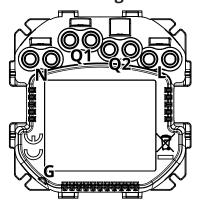
- **Do not** power the device before fully assembling it in the mounting box,
- Connect only in accordance with one of the diagrams,
- Install only in flush mounting boxes compliant with a relevant national safety standards and with depth no less than 40mm,
- **Do not** connect devices which are not compliant with the specification or relevant safety standards,
- **Do not** connect heating devices,
- **Do not** connect SELV or PELV circuits.
- Make sure you have all required parts when installing with covers other than FIBARO (see "Parts compatibility" on page 36).

Device parts:



1 – switch button, 2 – cover plate, 3 – unit (device), 4 – mounting frame

Notes for diagrams:



- N terminal for neutral wire
- **Q1** 1st output terminal motor
- **Q2** 2nd output terminal motor
- L terminal for live wire
- **G** groove used to measure wire length

4.2: Preparing for installation

Prepare wires by removing 11.5-13mm of insulation from their ends. You can use groove on the side of the unit to measure the length.

When installing with FIBARO or GIRA covers:

- 1. Pull out the switch button.
- 2. Take off the cover plate.

When installing with Legrand or Schneider covers:

- 1. Pull out the original switch button.
- 2. Take off the original cover plate.
- 3. Dismount the original mounting frame.
- 4. Snap the new mounting frame*.
 - * Additional mounting frames are sold separately.

4.3: Electrical connection

- 1. Switch off the mains voltage (disable the fuse).
- 2. Connect with the diagram:

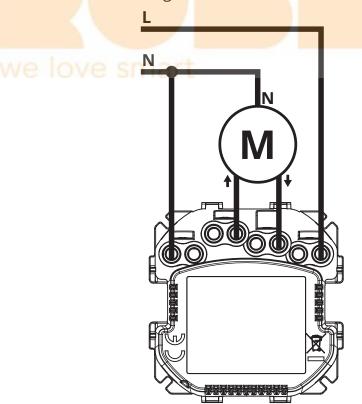


Diagram 1: Example connection with roller blind motor

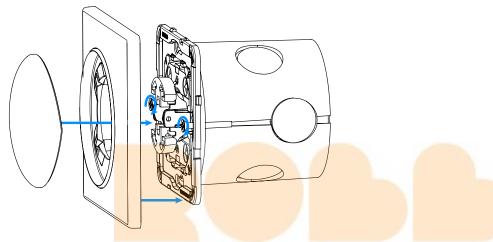
- 3. Verify correctness of connection.
- 4. Tighten the terminal screws using PH1 screwdriver.

4.4: Assembling the device

When installing the device in the mounting box orient the device with terminal screws going up or to the left (for horizontal button position) to ensure button order.

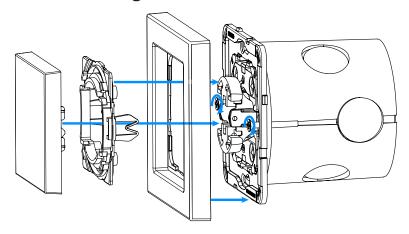
The light effect might look different for covers other than Walli. You can adjust colour and/or intensity of the LEDs to suit the particular cover (using parameters 11, 12, and 13) or disable it by changing parameter 13 to 0.

When installing with FIBARO covers:



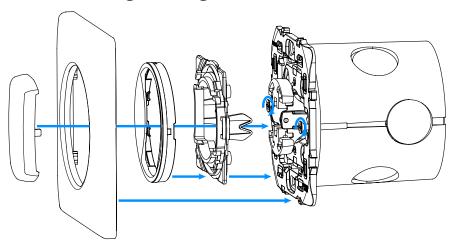
- 1. Insert the device with mounting frame into the mounting box and secure with mounting claws and screws.
- 2. Snap the cover plate to the device.
- 3. Snap the switch button to the device.

When installing with GIRA covers:



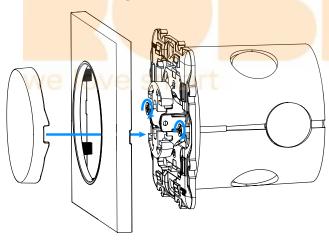
- 1. Insert the device with mounting frame into the mounting box and secure with mounting claws and screws.
- 2. Snap the new cover plate to the device.
- 3. Snap the switch button adapter* to the device.
- 4. Snap the new switch button to the device.

When installing with Legrand covers:



- 1. Insert the device with mounting frame* into the mounting box and secure with mounting claws and screws.
- 2. Snap the switch button adapter* to the device.
- 3. Snap the new inner cover plate to the device.
- 4. Snap the new outer cover plate to the device.
- 5. Snap the new switch button to the device.

When installing with Schneider covers:



- 1. Insert the device with mounting frame* into the mounting box and secure with mounting claws and screws.
- 2. Snap the new cover plate to the device.
- 3. Snap the new switch button to the device.
 - * Switch button adapter and additional mounting frames are sold separately.

4.5: Activating the device

- 1. If the device fully assembled, switch on the mains voltage.
- 2. LED ring light means the device is powered and can be added to the Z-Wave network.

5: Adding to Z-Wave network

Adding (Inclusion) – Z-Wave device learning mode, allowing to add the device to existing Z-Wave network.

5.1: Adding manually

To add the device to the Z-Wave network **manually**:

- 1. Power the device.
- 2. Set the main controller in (Security/non-Security Mode) add mode (see the controller's manual).
- 3. Quickly, three times click one of the buttons.
- 4. If you are adding in Security S2 Authenticated, input the underlined part of the DSK (label on the bottom of the box).
- 5. LED will start blinking yellow, wait for the adding process to end.
- 6. Adding result will be confirmed by the Z-Wave controller's message and the LED frame:
 - Green successful (non-secure, S0, S2 non-authenticated),
 - Magenta successful (Security S2 Authenticated),
 - Red not successful.

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5.2: Adding using SmartStart

SmartStart enabled products can be added into a Z-Wave network by scanning the Z-Wave QR Code present on the product with a controller providing SmartStart inclusion. SmartStart product will be added automatically within 10 minutes of being switched on in the network range.

To add the device to the Z-Wave network **using SmartStart**:

- 1. To use SmartStart your controller needs to support Security S2 (see the controller's manual).
- 2. Enter the full DSK string code to your controller. If your controller is capable of QR scanning, scan the QR code placed on the label on the bottom of the box.
- 3. Power the device.
- 4. Wait for the adding process to start (up to few minutes), which is signalled with yellow LED blinking.
- 5. Adding result will be confirmed by the Z-Wave controller's message and the LED frame:
 - Green successful (non-secure, S0, S2 non-authenticated),
 - Magenta successful (Security S2 Authenticated),
 - Red not successful.
 - In case of problems with adding the device, please reset the device and repeat the adding procedure.

6: Removing from Z-Wave network

Removing (Exclusion) – Z-Wave device learning mode, allowing to remove the device from existing Z-Wave network. Removing also results in resetting the device to factory defaults.

To **remove** the device from the Z-Wave network:

- 1. Power the device.
- 2. Set the main controller into remove mode (see the controller's manual).
- 3. Quickly, three times click one of the buttons.
- 4. LED will start blinking yellow, wait for the removing process to end.
- 5. Successful removing will be confirmed by the Z-Wave controller's message and red LED colour.



7: Calibration

Calibration is a process during which a device learns the position of the limit switches and a motor characteristic.

Calibration is mandatory in order for the device to correctly recognize a roller blind position.

The procedure consists of an automatic, full movement between the limit switches (up, down, and up again).

Button description:

- ▲ 1st button, for up movement
- ▼ 2nd button, for down movement

Automatic positioning of standard roller blind using the menu

- 1. Set parameter 151 to 1 (default).
- 2. Quickly, three times click, then press and hold one of the buttons to enter the menu.
- 3. Release button when the device glows white.
- 4. Quickly click the button to confirm.
- 5. The device will perform the calibration process, completing full cycle up, down and up again. During the calibration the LED frame blinks white.
- 6. Test whether the positioning works correctly.

Automatic positioning of standard roller blind using the parameter

- 1. Set parameter 151 to 1 (default).
- 2. Set parameter 150 to 2.
- 3. The device will perform the calibration process, completing full cycle up, down and up again. During the calibration the LED frame blinks white.
- 4. Test whether the positioning works correctly.

Manual positioning of slats in venetian blinds mode

- 1. Set parameter 151 to 2.
- 2. Calibrate blinds as standard ones (described above).
- 3. By default, time of transition between extreme positions is set to 150 (1.5 seconds) in parameter 152.
- 4. Turn slats between extreme positions by holding \triangle or ∇ button:
 - If after full cycle a blind starts moving up or down decrease value of parameter 152,
 - If after full cycle the slats does not reach end positions increase value of parameter 152,

- 5. Repeat previous step until satisfactory positioning is achieved.
- 6. Test whether the positioning works correctly. Correctly configured slats should not force the blinds to move up or down.

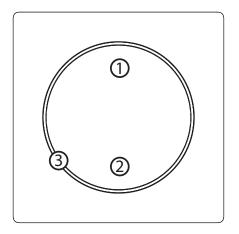
Manual positioning of roller blind with built-in driver

- 1. Set parameter 151 to 5 or 6.
- 2. By default, time of transition between extreme positions is set to 6000 (60 seconds) in parameters 156 and 157.
- 3. Move roller blinds between extreme positions by clicking ▲ or ▼ switch:
 - If roller blind stops before reaching top increase value of parameter 156,
 - If roller blind does not stop after reaching top decrease value of parameter 156,
 - If roller blind stops before reaching bottom increase value of parameter 157,
 - If roller blind does not stop after reaching bottom decrease value of parameter 157,
- 4. Repeat previous step until satisfactory positioning is achieved.
- 5. Test whether the positioning works correctly.

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8: Operating the device

8.1: Controls



- 1. First/UP/▲ button,
- 2. Second/DOWN/▼ button,
- 3. LED ring.

8.2: Button control

Operating roller blinds (configurable using parameter 24)

- Click ▲ initiate up movement.
- Click ▼ initiate down movement.

If the blind is moving, clicking any button, will stop the movement.

Operating slats of venetian blinds

- Hold ▲ initiate slats rotation up.
- Hold ▼ initiate slats rotation down.

Release to stop the movement.

Other actions

Perform following actions on one of the buttons to:

- 3xClick start learn mode to add/remove to/from Z-Wave network,
- 1,2,3xClick/hold/release activate scene in the controller for specific action (requires configuration using parameters 40 and 41)
- 3xClick then press and hold enter the menu.

8.3: Visual indications

The built-in LED light shows current device status.

After powering the device:

• Green – device added to a Z-Wave network (non-secure, S0, S2 non-authenticated),

- Magenta device added to a Z-Wave network (Security S2 Authenticated),
- Red device not added to a Z-Wave network.

State of the device:

 White – load turned ON (configurable using parameters 11 and 12).

Update:

- Blinking cyan update in progress,
- · Green update successful,
- Red update not successful.

Menu:

- Blinking green entering the menu (added as non-secure, S0, S2 non-authenticated),
- Blinking magenta entering the menu (added as Security S2 Authenticated),
- Blinking red entering the menu (not added to a Z-Wave network),
- White start calibration,
- Green reset energy consumption memory,
- Yellow reset to factory defaults.

8.4: Menu We love smar

Menu allows to perform Z-Wave network actions. In order to use the menu:

- 1. Quickly, three times click, then press and hold one of the buttons to enter the menu, device blinks to signal adding status (see 8.3: Visual indications).
- 2. Release the button when device signals desired position with colour:
 - WHITE start calibration
 - GREEN reset energy consumption memory
 - **YELLOW** reset to factory defaults
- 3. Quickly click the button to confirm.

8.5: Resetting to factory defaults

Reset procedure allows to restore the device back to its factory settings, which means all information about the Z-Wave controller and user configuration will be deleted. Resetting to factory defaults does not reset energy consumption memory.

- Resetting the device is not the recommended way of removing the device from the Z-Wave network. Use reset procedure only if the primary controller is missing or inoperable. Certain device removal can be achieved by the procedure of removing described.
- 1. Quickly, three times click, then press and hold one of the buttons to enter the menu.
- 2. Release button when the device glows yellow.
- 3. Quickly click the button to confirm.
- 4. After few seconds the device will be restarted, which is signalled with red LED colour.



9: Power and energy metering

The device allows for the active power and energy consumption monitoring. Data is sent to the main Z-Wave controller, e.g. Home Center.

Measuring is carried out by the most advanced microcontroller technology, assuring maximum accuracy and precision (+/- 1% for loads greater than 10W).

Electric active power – power that energy receiver is changing into a work or a heat. The unit of active power is Watt [W].

Power measurement can contain mains voltage fluctuations within +/- 10%.

Electric energy – energy consumed by a device through a time period. Consumers of electricity in households are billed by suppliers on the basis of active power used in given unit of time. Most commonly measured in kilowatt-hour [kWh]. One kilowatt-hour is equal to one kilowatt of power consumed over period of one hour, 1kWh = 1000Wh.

Resetting consumption memory:

- 1. Quickly, three times click, then press and hold one of the buttons to enter the menu.
- 2. Release button when the device glows green.
- 3. Quickly click the button to confirm.
- 4. Device will blink two times green to confirm.

| i | The device stores periodically (every hour) the consumption data in the device memory. Disconnecting |
|-----|--|
| | sumption data in the device memory. Disconnecting |
| the | module from the power supply will not erase stored |
| ene | rgy consumption data. |

10: Configuration

10.1: Associations

Association (linking devices) – direct control of other devices within the Z-Wave system network.

Associations allow:

- reporting the device status to the Z-Wave controller (using Lifeline group),
- creating simple automations by controlling other devices without participation of the main controller (using groups assigned to actions on the device).

Commands send to 2nd and 3rd association groups reflect button operation according to device configuration, e.g. starting the blinds movement using button will send frame responsible for the same action.

The device provides the association of 3 groups:

1st association group - "Lifeline" reports the device status and allows for assigning single device only (main controller by default).

2nd association group – "Roller Shutter" is assigned to shutter position control – UP/DOWN (uses Switch Multilevel command class).

3rd association group – "Slats" is assigned to slats position control – UP/DOWN (uses Switch Multilevel command class).

The device allows to control 5 regular or multichannel devices per an association group, with the exception of "LifeLine" that is reserved solely for the controller and hence only 1 node can be assigned.

Assocation groups mapping

| Root | Endpoint | Association group in endpoint |
|---------------------|------------|-------------------------------|
| Association Group 2 | Endpoint 1 | Association Group 2 |
| Association Group 3 | Endpoint 2 | Association Group 2 |

Switch Multilevel commands sent to association groups for parameter 151 set to 1, 5 or 6

| | Click | Hold | Release |
|-------------------|---------------------------------|----------------------------|---------------------------|
| Button 1 and 2 | Start/Stop Level Change: 2nd | Start Level Change: 3rd | Stop Level Change: 3rd |
| | group | group | group |

Switch Multilevel commands sent to association groups for parameter 151 set to 2

| | Click | Hold | Release |
|-------------------|--|------|-------------------------|
| Button 1 and 2 | Start/Stop Level Change: 2nd group | - | Set Level: 3rd group |



10.2: Advanced parameters

The device allows customizing its operation to user's needs using configurable parameters.

The settings can be adjusted via the Z-Wave controller to which the device is added. The way of adjusting them might differ depending on the controller.

In the FIBARO interface parameters are presented as simple options in the Advanced Settings of the device.

Available parameters:

| 11. | | LED frame - colour when moving |
|---------|----------|---|
| Descri | ption | This parameter defines the LED colour when the motor is running. |
| Parame | ter size | 1B |
| Default | value | 1 (white) |
| | | 0 – LED disabled |
| | | 1 – White |
| | | 2 – Red |
| Avail | able | 3 – Green |
| valu | ies | 4 – Blue |
| we I | | 5 – Yellow 6 – Cyan |
| | | 7 – Magenta |
| 12. | | LED frame – colour when not moving |
| Descri | ption | This parameter defines the LED colour when the device motor is not running. |
| Parame | ter size | 1B |
| Default | value | 0 (disabled) |
| | | 0 – LED disabled |
| | | 1 – White |
| | | 2 – Red |
| Avail | able | 3 – Green |
| valu | ıes | 4 – Blue |
| | | 5 – Yellow |
| | | 6 – Cyan |
| | | 7 – Magenta |

| 13. | | LED frame - brightness | | |
|-----------------------------|-----------|--|--|--|
| Descr | iption | This parameter allows to adjust the LED frame brightness. | | |
| Parame | eter size | 1B | | |
| Defaul | t value | 100 (100%) | | |
| Avai | lable | 0 – LED disabled | | |
| val | ues | 1-100 (1-100% brightness) | | |
| 24. | | Buttons orientation | | |
| Descr | iption | This parameter allows reversing the operation of the buttons. | | |
| Parame | eter size | 1B | | |
| Defaul | t value | 0 | | |
| Avai | lable | 0 – default (1st button UP, 2nd button DOWN) | | |
| val | ues | 1 – reversed (1st button DOWN, 2nd button UP) | | |
| 25. | | Outputs orientation | | |
| Descr | iption | This parameter allows reversing the operation of Q1 and Q2 without changing the wiring (e.g. in case of invalid motor connection). | | |
| Parameter <mark>size</mark> | | 1B | | |
| Default val <mark>ue</mark> | | 0 | | |
| Avai | lable | 0 - default (Q1 – UP, Q2 – DOWN) | | |
| val | ues | 1 - reversed (Q1 – DOWN, Q2 – UP) | | |

| 30. | | Alarm configuration - 1st slot |
|---------------------|----------|--|
| Description | | This parameter determines to which alarm frames and how the device should react. The parameters consist of 4 bytes, three most significant bytes are set according to the official Z-Wave protocol specification. |
| Paramet | ter size | 4B |
| Default | value | [0x00, 0x00, 0x00, 0x00] (disabled) |
| | | 1B [MSB] – Notification Type |
| | | 2B – Notification Status |
| | | 3B – Event/State Parameters |
| Avail | ahle | 4B [LSB] – action: |
| Available values | | 0x00 - no action, 0xX1 - open, 0xX2 - close, 0x0X - no action on LED frame, 0x1X - LED frame blinks red, 0x2X - LED frame blinks green, 0x4X - LED frame blinks blue, 0x8X - dis- able LED frame, 0xFX - LED frame LAPD signal (red-white-blue) |
| 31. | | Alarm configurati <mark>on - 2nd</mark> slot |
| Descri | | This parameter determines to which alarm frames and how the device should react. The parameters consist of 4 bytes, three most significant bytes are set according to the official Z-Wave protocol specification. |
| Paramet | ter size | 4B |
| Defaula | | [0x05, 0xFF, 0x00, 0x00] |
| Default | value | (Water Alarm, any notification, no action) |
| | | 1B [MSB] – Notification Type |
| | | 2B – Notification Status |
| | | 3B – Event/State Parameters |
| Availa | able | 4B [LSB] – action: |
| valu | | 0x00 - no action, 0xX1 - open, 0xX2 - close, 0x0X - no action on LED frame, 0x1X - LED frame blinks red, 0x2X - LED frame blinks green, 0x4X - LED frame blinks blue, 0x8X - dis- able LED frame, 0xFX - LED frame LAPD signal (red-white-blue) |

| 32. | | | Alarm configuration - 3rd slot |
|-------------|---------------------|------|--|
| Description | | on | This parameter determines to which alarm frames and how the device should react. The parameters consist of 4 bytes, three most significant bytes are set according to the official Z-Wave protocol specification. |
| Parame | eter | size | 4B |
| Defaul | t val | ue | [0x01, 0xFF, 0x00, 0x00] (Smoke Alarm, any notification, no action) |
| | | | 1B [MSB] – Notification Type |
| | | | 2B – Notification Status |
| | | | 3B – Event/State Parameters |
| A | اماما | _ | 4B [LSB] – action: |
| | Available values | | 0x00 – no action, 0xX1 – open, 0xX2 – close, 0x0X – no action on LED frame, 0x1X – LED frame blinks red, 0x2X – LED frame blinks green, 0x4X – LED frame blinks blue, 0x8X – dis- |
| | | | able LED frame, 0xFX – LED frame LAPD signal (red-white-blue) |
| 33. | | | Alarm configuration - 4th slot |
| Descr | Description | | This parameter determines to which alarm frames and how the device should react. The parameters consist of 4 bytes, three most significant bytes are set according to the official Z-Wave protocol specification. |
| Parame | eter | size | 4B |
| Defeul | 4 1 | l | [0x02, 0xFF, 0x00, 0x00] |
| Defaul | t vai | ue | (CO Alarm, any notification, no action) |
| | | | 1B [MSB] – Notification Type |
| | | | 2B – Notification Status |
| | | | 3B – Event/State Parameters |
| Avai | Available | 2 | 4B [LSB] – action: |
| values | | | <pre>0x00 - no action, 0xX1 - open, 0xX2 - close, 0x0X - no action on LED frame, 0x1X - LED frame blinks red, 0x2X - LED frame blinks green, 0x4X - LED frame blinks blue, 0x8X - disable LED frame, 0xFX - LED frame LAPD signal (red-white-blue)</pre> |

| 34. | | Alarm configuration - 5th slot |
|---------------------|-----------|--|
| Description | | This parameter determines to which alarm frames and how the device should react. The parameters consist of 4 bytes, three most significant bytes are set according to the official Z-Wave protocol specification. |
| Parame | eter size | 4B |
| Defaul | t value | [0x04, 0xFF, 0x00, 0x00] (Heat Alarm, any notification, no action) |
| | | 1B [MSB] – Notification Type |
| | | 2B – Notification Status |
| | | 3B – Event/State Parameters |
| Δναί | lahle | 4B [LSB] – action: |
| Available values | | 0x00 – no action, 0xX1 – open, 0xX2 – close, 0x0X – no action on LED frame, 0x1X – LED frame blinks red, 0x2X – LED frame blinks green, 0x4X – LED frame blinks blue, 0x8X – dis- able LED frame, 0xFX – LED frame LAPD signal |
| 25 | | (red-white-blue) |
| 35. | | Alarm configuration – duration |
| Description | | This parameter defines duration of alarm sequence. When time set in this parameter elapses, alarm is cancelled, LED frame and relay restore normal operation, but do not recover state from before the alarm. |
| Parameter size | | 2B |
| Defaul | t value | 600 (10min) |
| Avai | lable | 0 – infinite |
| values | | 1-32400 (1s-9h, 1s step) – duration |

| 40. | | First button – scenes sent | | |
|------------------|--|---|--|--|
| Description | | This parameter determines which actions result in sending scene IDs assigned to them. Values can be combined (e.g. 1+2=3 means that scenes for single and double click are sent). | | |
| | | Enabling scenes for triple click disables entering the device in learn mode by triple clicking. | | |
| Parame | eter size | 1B | | |
| Defaul | t value | 0 (no scenes) | | |
| | | 1 – Key pressed 1 time | | |
| Avai | lable | 2 – Key pressed 2 times | | |
| val | ues | 4 – Key pressed 3 times | | |
| | | 8 – Key hold down and key released | | |
| 41. | | Second button – scenes sent | | |
| Descr | riptio <mark>n</mark> | This parameter determines which actions result in sending scene IDs assigned to them. Values can be combined (e.g. 1+2=3 means that scenes for single and double click are sent). | | |
| | | Enabling scenes for triple click disables entering the device in learn mode by triple clicking. | | |
| Parame | eter <mark>size</mark> | 1B | | |
| Defaul | t val <mark>ue</mark> 🦲 | 0 (no scenes) | | |
| | | 1 – Key pressed 1 time | | |
| Avai | lable | 2 – Key pressed 2 times | | |
| val | ues | 4 – Key pressed 3 times | | |
| | | 8 – Key hold down and key released | | |
| 60. | Power reports – include self-consumption | | | |
| Description | | This parameter determines whether the power measurements should include power consumed by the device itself. | | |
| Parame | eter size | 1B | | |
| Defaul | t value | 0 (not included) | | |
| Available values | | 0 – self-consumption not included 1 – self-consumption included | | |

| 61. | | Power reports - on change | |
|-------------------------------|-----------|--|--|
| Description | | This parameter defines minimal change (from the last reported) in measured power that results in sending new report. For loads under 50W the parameter is irrelevant, report are sent every 5W change. | |
| Parame | eter size | 2B | |
| Defaul | t value | 15 (15%) | |
| | lable | 0 - reporting on change disabled | |
| val | ues | 1-500 (1-500%, 1% step) – minimal change | |
| 62. | | Power reports – periodic | |
| Descr | ription | This parameter defines reporting interval for measured power. Periodic reports are independent from changes in value (parameter 61). | |
| Parame | eter size | 2B | |
| Defaul | lt value | 3600 (1h) | |
| Avai | lable | 0 – periodic reports disabled | |
| val | ues | <mark>30-324</mark> 00 (30s-9h, 1s s <mark>tep) – ti</mark> me interval | |
| 65. | | Energy reports – on change | |
| Descr | iption | This parameter defines minimal change (from the last reported) in measured energy that results in sending new report. | |
| Parame | eter size | 2B | |
| Defaul | t value | 10 (0.1kWh) | |
| Avai | lable | 0 - reporting on change disabled | |
| _ | ues | 1-500 (0.01-5kWh, 0.01kWh step) – minimal change | |
| 66. Energy reports – periodic | | Energy reports - periodic | |
| Description | | This parameter defines reporting interval for measured energy. Periodic reports are independent from changes in value (parameter 65). | |
| Parameter size | | 2B | |
| Defaul | lt value | 3600 (1h) | |
| Avai | lable | 0 – periodic reports disabled | |
| values | | 30-32400 (30s-9h, 1s step) – time interval | |

| 150. | | Force calibration | |
|------------------|--------------|--|--|
| Description | | By setting this parameter to 2 the device enters the calibration mode. The parameter relevant only if the device is set to work in positioning mode (parameter 151 set to 1 or 2). | |
| Parame | eter size | 1B | |
| Defaul | lt value | 0 | |
| | | 0 - device is not calibrated | |
| _ | lable ues | 1 - device is calibrated | |
| Val | ucs | 2 - force device calibration | |
| 151. | | Operating mode | |
| Description | | This parameter allows adjusting operation according to the connected device. | |
| Parame | eter size | 1B | |
| Defaul | lt value | 1 | |
| | | 1 – roller blind (with positioning) | |
| Avai | lable | 2 – Venetian blind (with positioning) | |
| val | ues | 5 – roller blind with built-in driver | |
| | | 6 – roller blind with built-in driver (impulse) | |
| 152. | Ver | netian blind – time of full turn of the slats | |
| Description | | For Venetian blinds (parameter 151 set to 2) the parameter determines time of full turn cycle of the slats. | |
| | | The parameter is irrelevant for other modes. | |
| Parameter size | | 4B | |
| Defaul | lt value | 150 (1.5 seconds) | |
| Available values | | 0-65535 (0 - 655.35s, every 0.01s) - time of turn | |

| 153. | | Set slats back to previous position | | |
|---------------------|----------|--|--|--|
| Description | | For Venetian blinds (parameter 151 set to 2) the parameter determines slats positioning in various situations. | | |
| | | The parameter is irrelevant for other modes. | | |
| Parame | ter size | 1B | | |
| Defaul | t value | 1 | | |
| Available values | | 0 – slats return to previously set position only in case of the main controller operation | | |
| | | 1 – slats return to previously set position in case of the main controller operation, momentary switch operation, or when the limit switch is reached | | |
| | | 2 – slats return to previously set position in case of the main controller operation, momentary switch operation, when the limit switch is reached or after receiving the Switch Multilevel Stop control frame | | |
| 154. | De | lay motor stop after reaching end switch | | |
| Descr | iption | The parameter determines the time after which the motor will be stopped after end switch contacts are closed. | | |
| Parame | ter size | 2B | | |
| Defaul | t value | 10 (1 second) | | |
| Avail val | | 1-255 (0.1s - 25.5 seconds) | | |
| 155. | | Motor operation detection | | |
| Description | | Power threshold interpreted as reaching a limit switch. | | |
| Parame | ter size | 2B | | |
| Defaul | t value | 10 (10W) | | |
| Avai | lable | 1-255 (1-255W) - report interval | | |
| val | ues | 0 - no detection | | |

| 156. | | Time of up movement | | |
|-----------------------------|-----------|--|--|--|
| Description | | This parameter determines the time needed for roller blinds to reach the top. For modes with positioning value is set automatically during calibration, otherwise, it must be set manually. | | |
| Parame | eter size | 4B | | |
| Defaul | lt value | 6000 (60 seconds) | | |
| Available values | | 1-65535 (0.01 - 655.35 seconds) | | |
| 157. | | Time of down movement | | |
| Description | | This parameter determines the time needed for roller blinds to reach the bottom. For modes with positioning value is set automatically during calibration, otherwise, it must be set manually. | | |
| Parameter size | | 4B | | |
| Default val <mark>ue</mark> | | 6000 (60 seconds) | | |
| Available values | | 1-65535 (0.01 - 655.35 seconds) | | |

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11: Z-Wave specification

Endpoint 1:

Generic Device Class: GENERIC_TYPE_SWITCH_MULTILEVEL

Specific Device Class: SPECIFIC_TYPE_CLASS_B_MOTOR_CONTROL

Description: control up/down

Endpoint 2:

Generic Device Class: GENERIC_TYPE_SWITCH_MULTILEVEL

Specific Device Class: SPECIFIC_TYPE_CLASS_B_MOTOR_CONTROL

Description: control tilt.

Switch Multilevel Command Class values refers to:

0x00 - fully close

• 0x63 - fully open

Supported Command Classes

| Command Class | Version | Secure |
|--|---------|--------|
| COMMAND_C <mark>LASS_ZWA</mark> VEPLUS_INFO [0x5E] | V2 | |
| COMMAND_CLASS_SWITCH_MULTILEVEL [0x26] | V4 | YES |
| COMMAND_C <mark>LASS_ASSOCIATION [0x8</mark> 5] | V2 | YES |
| COMMAND_C <mark>LASS_MUL</mark> TI_CHANNEL_ASSOCIA- TION [0x8E] | V3 | YES |
| COMMAND_CLASS_ASSOCIATION_GRP_INFO [0x59] | V2 | YES |
| COMMAND_CLASS_TRANSPORT_SERVICE [0x55] | V2 | |
| COMMAND_CLASS_VERSION [0x86] | V2 | YES |
| COMMAND_CLASS_MANUFACTURER_SPECIFIC [0x72] | V2 | YES |
| COMMAND_CLASS_DEVICE_RESET_LOCALLY [0x5A] | V1 | YES |
| COMMAND_CLASS_POWERLEVEL [0x73] | V1 | YES |
| COMMAND_CLASS_SECURITY [0x98] | V1 | |
| COMMAND_CLASS_SECURITY_2 [0x9F] | V1 | |
| COMMAND_CLASS_SUPERVISION [0x6C] | V1 | |
| COMMAND_CLASS_METER [0x32] | V3 | YES |
| COMMAND_CLASS_CONFIGURATION [0x70] | V1 | YES |
| COMMAND_CLASS_CRC_16_ENCAP [0x56] | V1 | |

| COMMAND_CLASS_NOTIFICATION [0x71] | V8 | YES |
|--|----|-----|
| COMMAND_CLASS_PROTECTION [0x75] | V2 | YES |
| COMMAND_CLASS_MULTI_CHANNEL [0x60] | V4 | YES |
| COMMAND_CLASS_CENTRAL_SCENE [0x5B] | V3 | YES |
| COMMAND_CLASS_FIRMWARE_UPDATE_MD [0x7A] | V4 | YES |
| COMMAND_CLASS_APPLICATION_STATUS [0x22] | V1 | |
| COMMAND_CLASS_BASIC [0x20] | V1 | YES |

Multichannel Command Class

| Command Class | Version | Secure | | |
|---|---------|--------|--|--|
| Endpoint 1 | | | | |
| COMMAND_CLASS_ZWAVEPLUS_INFO [0x5E] | V2 | | | |
| COMMAND_CLASS_SWITCH_MULTILEVEL [0x26] | V4 | YES | | |
| COMMAND_CLASS_ASSOCIATION [0x85] | V2 | YES | | |
| COMMAND_CLASS_MULTI_CHANNEL_ASSOCIA- TION [0x8E] | V3 | YES | | |
| COMMAND_CLASS_ASSOCIATION_GRP_INFO [0x59] | V2 | YES | | |
| COMMAND_CLASS_SECURITY [0x98] | V1 | | | |
| COMMAND_CLASS_SECURITY_2 [0x9F] | V1 | | | |
| COMMAND_CLASS_SUPERVISION [0x6C] | V1 | | | |
| COMMAND_CLASS_METER [0x32] | V3 | YES | | |
| COMMAND_CLASS_NOTIFICATION [0x71] | V8 | YES | | |
| COMMAND_CLASS_APPLICATION_STATUS [0x22] | V1 | | | |
| Endpoint 2 | | | | |
| COMMAND_CLASS_ZWAVEPLUS_INFO [0x5E] | V2 | | | |
| COMMAND_CLASS_SWITCH_MULTILEVEL [0x26] | V4 | YES | | |
| COMMAND_CLASS_ASSOCIATION [0x85] | V2 | YES | | |
| COMMAND_CLASS_MULTI_CHANNEL_ASSOCIA-TION [0x8E] | V3 | YES | | |
| COMMAND_CLASS_ASSOCIATION_GRP_INFO [0x59] | V2 | YES | | |
| COMMAND_CLASS_SECURITY [0x98] | V1 | | | |
| COMMAND_CLASS_SECURITY_2 [0x9F] | V1 | | | |
| COMMAND_CLASS_SUPERVISION [0x6C] | V1 | | | |
| COMMAND_CLASS_APPLICATION_STATUS [0x22] | V1 | | | |

Notification Command Class

The device uses Notification Command Class to report different events to the controller ("Lifeline" group).

| Notification Type | Event | Parameter | Status | In endpoints |
|-------------------------|---|-----------|--|-----------------------|
| Power Management [0x08] | Over-current de- tected [0x06/V3] | | 0xFF – enable (non-change- able) | Root, End- point 1 |
| System [0x09] | System hardware failure with man- ufacturer propri- etary failure code [0x03] | 0x01 | 0xFF – enable (non-change- able) | Root, End- point 1 |

Protection CC

Protection Command Class allows to prevent local or remote control of the outputs.

| Туре | State | Description | Hint | |
|-------|-------|--|--|--|
| Local | 0 | Unprotected - The device is not protected, and may be operated normally via the user interface. Buttons connected with output | | |
| Local | 2 | No operation possible – button can not change relay state, any other functionality is available (menu). | Buttons discon- nected from outputs. | |
| RF | 0 | Unprotected - The device accept and respond to all RF Commands. | Outputs can be controlled via Z-Wave. | |
| RF | 1 | No RF control – command class basic and switch binary are rejected, every other command class will be handled. | Outputs cannot be controlled via Z-Wave. | |

Meter CC

Same for Root, Endpoint 1 and Endpoint 2.

| Meter Type | Scale | Rate Type | Precision | Size |
|--------------------|-------------------------------------|------------------|-----------|------|
| Electric [0x01] | Electric_kWh [0x00] (default) | Import [0x01] | 2 | 4 |
| Electric [0x01] | Electric_W [0x02] | Import [0x01] | 1 | 2 |

12: Parts compatibility

| Available FIBA | Included in | | |
|----------------------------------|---------------------|------------|--|
| Name | Symbol | FGWREU-111 | |
| Walli Roller Shutter Unit | FG-WREU111-AS-8001 | Х | |
| Switch Button with Lightguide | FG-WDSEU221-AS-8100 | Х | |
| Switch Button Adapter | FG-WDSEU221-PP-0007 | | |
| Mounting Frame FIBARO/ GIRA | FG-Wx-AS-4001 | Х | |
| Mounting Frame Legrand | FG-Wx-AS-4002 | | |
| Mounting Frame Schneider | FG-Wx-AS-4003 | | |
| Single Cover Plate | FG-Wx-PP-0001 | Х | |
| Double Cover Plate | FG-Wx-PP-0003 | | |
| Triple Cover Plate | FG-Wx-PP-0004 | | |

Parts required for GIRA System 55 (only with non-metalised outer surface: Standard 55, E2, Event, Event Clear) selected covers*

| Required FIBARO parts | | | |
|----------------------------|---|---------------------|--|
| Name | | Symbol | |
| Walli Roller Shutter Unit | | FG-WREU1111-AS-8001 | |
| Switch Button Adapter | J | FG-WDSEU221-PP-0007 | |
| Mounting Frame FIBARO/GIRA | | FG-Wx-AS-4001 | |

Parts required for Legrand Céliane selected covers*

| Required FIBARO parts | | | |
|---------------------------|---------------------|--|--|
| Name | Symbol | | |
| Walli Roller Shutter Unit | FG-WREU111-AS-8001 | | |
| Switch Button Adapter | FG-WDSEU221-PP-0007 | | |
| Mounting Frame Legrand | FG-Wx-AS-4002 | | |

Parts required for Schneider Odace selected covers*

| Required FIBARO parts | | | |
|---------------------------|--------------------|--|--|
| Name | Symbol | | |
| Walli Roller Shutter Unit | FG-WREU111-AS-8001 | | |
| Mounting Frame Schneider | FG-Wx-AS-4003 | | |

^{*} Go to manuals.fibaro.com/walli-roller-shutter/ for the list of compatible parts or contact our support team.

13: Regulations

Legal Notices

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Declaration of conformity

Hereby, Fibar Group S.A. declares that the device is in compliance with the essential requirements and other relevant provisions of Directive 2014/53/EU. The full text of the EU declaration of conformity is available at the following internet address: www.manuals.fibaro.com

WEEE Directive Compliance

Device labelled with this symbol should not be disposed with other household wastes. It shall be handed over to the applicable collection point for the recycling of waste electrical and electronic equipment.

